

LRT0100AL-AE53CT10A Datasheet



- 100, 250, 500, 750, 1000, 1500 mm travel
- 20 μm full travel accuracy
- 300 kg load capacity
- Includes stainless steel dust covers
- Ball screw and lead screw configurations
- Integrated linear encoders with 50 nm resolution provide slip/stall detection and position correction
- Optional integrated power-off brake for vertical applications
- Designed for use with an X-MCC Series controller for coordinated motion
- With AutoDetect, the X-MCC controller configures its settings automatically for the connected peripheral

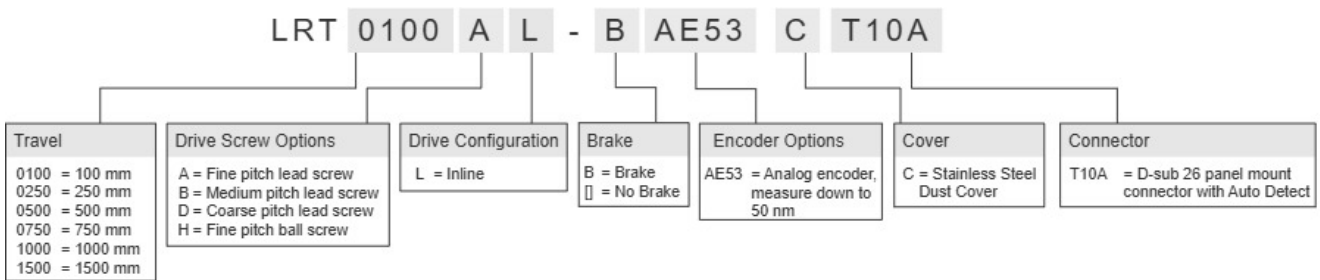
LRT-AEC Series Overview

Zaber's LRT-AEC Series are computer-controlled, motorized linear stages designed for positioning high loads to within 20 µm accuracy. An integrated linear encoder combined with stage calibration provides high accuracy positioning over the full travel of the device. They have low pitch, roll, yaw and runout and long lifetime. Flexible dust covers keep out moderate debris. An optional power-off brake is available to enable vertical applications with backdrivable screws.

The stages are designed to connect directly to our X-MCC Series universal motor controllers, or they can be used with third party 2-phase stepper motor controllers through the panel mount DB26 connector. Set up is easy with AutoDetect. Once connected, the X-MCC controller will automatically detect and configure the LRT-AEC.

For more information visit: <https://www.zaber.com/products/linear-stages/LRT-AEC>

LRT-AEC Series Part Numbering & Options



LRT0100AL-AE53CT10A Drawings

- [LRT-AECT10A.png \(Drawing for the LRT-AECT10A\)](#)

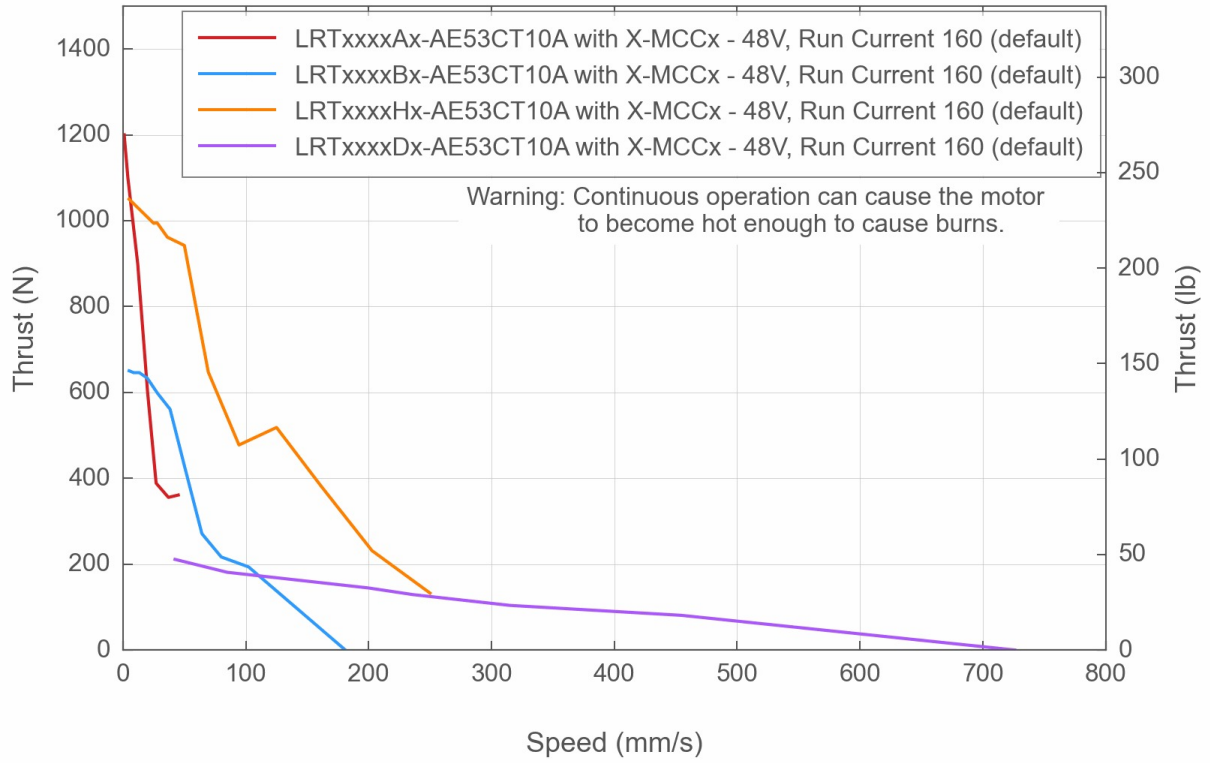
LRT0100AL-AE53CT10A Specifications

| | |
|--------------------------------------------|---------------------------------------------|
| Microstep Size (Default Resolution) | 0.124023438 μm |
| Built-in Controller | No |
| Recommended Controller | X-MCC (48 V) Recommended |
| AutoDetect | Yes |
| Travel Range | 100 mm (3.937") |
| Accuracy (unidirectional) | 20 μm (0.000787") |
| Repeatability | < 1 μm (< 0.000039") |
| Minimum Incremental Move | 500 nm |
| Backlash | < 15 μm (< 0.000591") |
| Maximum Speed | 45 mm/s (1.772"/s) |
| Minimum Speed | 0.0000757 mm/s (0.000003"/s) |
| Speed Resolution | 0.0000757 mm/s (0.000003"/s) |
| Encoder Type | Linear analog encoder |
| Encoder Resolution | 50 nm |
| Peak Thrust | 1200 N (269.1 lb) |
| Back-driving Force* | Non-back-driving |
| Maximum Continuous Thrust | 1200 N (269.1 lb) |
| Maximum Centered Load | 2940 N (659.3 lb) |
| Maximum Moment (Pitch) | 70 N-m (51.7 ft-lb) |
| Maximum Moment (Roll) | 80 N-m (59.0 ft-lb) |
| Maximum Moment (Yaw) | 70 N-m (51.7 ft-lb) |
| Vertical Runout | < 10 μm (< 0.000394") |
| Horizontal Runout | < 50 μm (< 0.001968") |
| Pitch | 0.015° (0.262 mrad) |
| Roll | 0.02° (0.349 mrad) |
| Yaw | 0.03° (0.523 mrad) |
| Stiffness in Pitch | 1400 N-m/° (12 $\mu\text{rad/N-m}$) |
| Stiffness in Roll | 700 N-m/° (25 $\mu\text{rad/N-m}$) |
| Stiffness in Yaw | 1200 N-m/° (15 $\mu\text{rad/N-m}$) |
| Linear Motion Per Motor Rev | 1.5875 mm (0.062") |
| Motor Steps Per Rev | 200 |

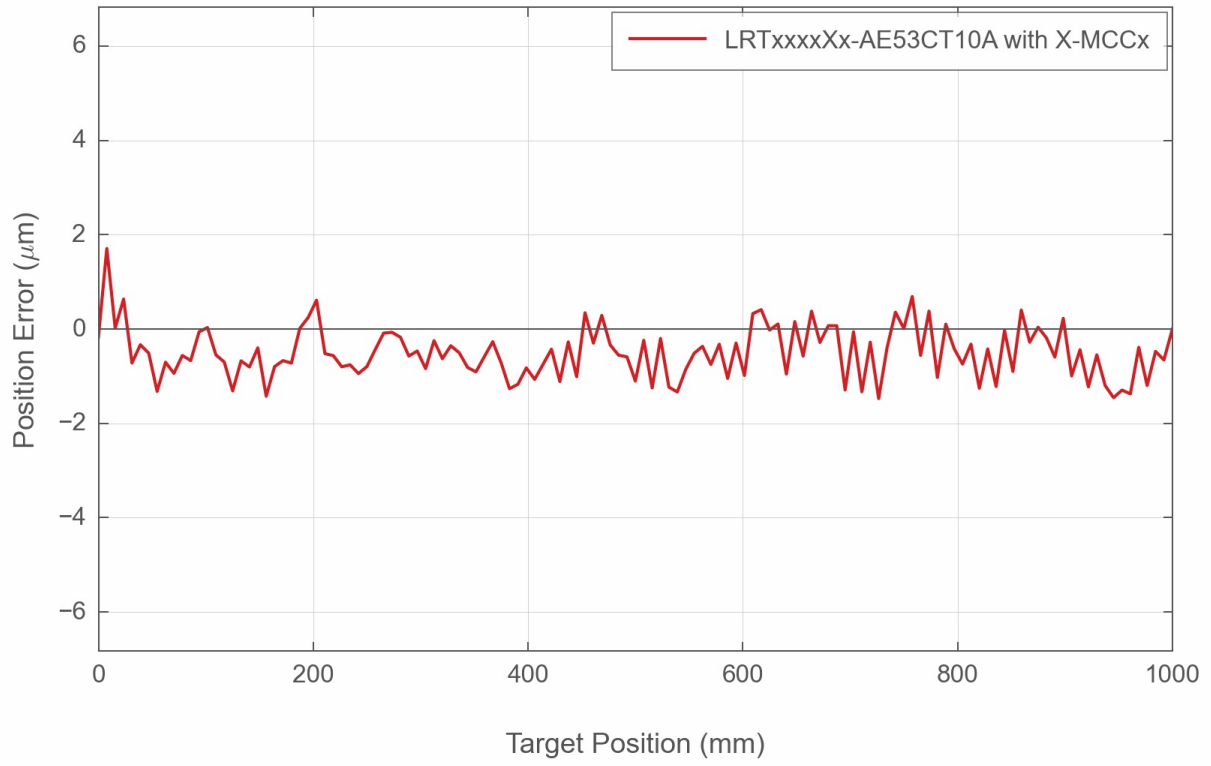
| | |
|--------------------------------------------|---------------------------------------------|
| Microstep Size (Default Resolution) | 0.124023438 μm |
| Motor Type | Stepper (2-phase) |
| Motor Rated Current | 3000 mA/phase |
| Inductance | 2 mH/phase |
| Motor Connection | D-sub 26 |
| Guide Type | Recirculating Ball Linear Guide |
| Limit or Home Sensing | Linear Encoder Index Mark |
| Axes of Motion | 1 |
| LED Indicators | No |
| Operating Temperature Range | 0 to 50 °C |
| CE Compliant | Yes |
| Vacuum Compatible | No |
| Weight | 3.65 kg (8.047 lb) |

LRT-AEC Series Charts

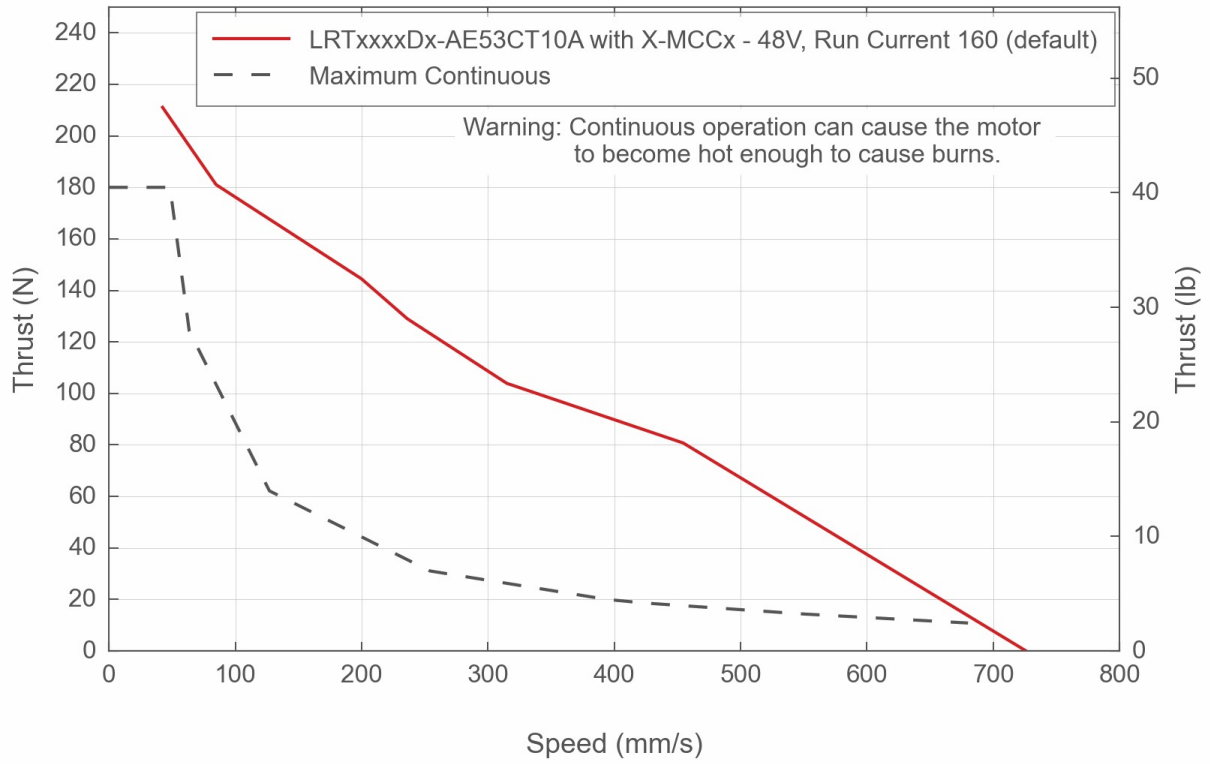
Thrust Speed Performance



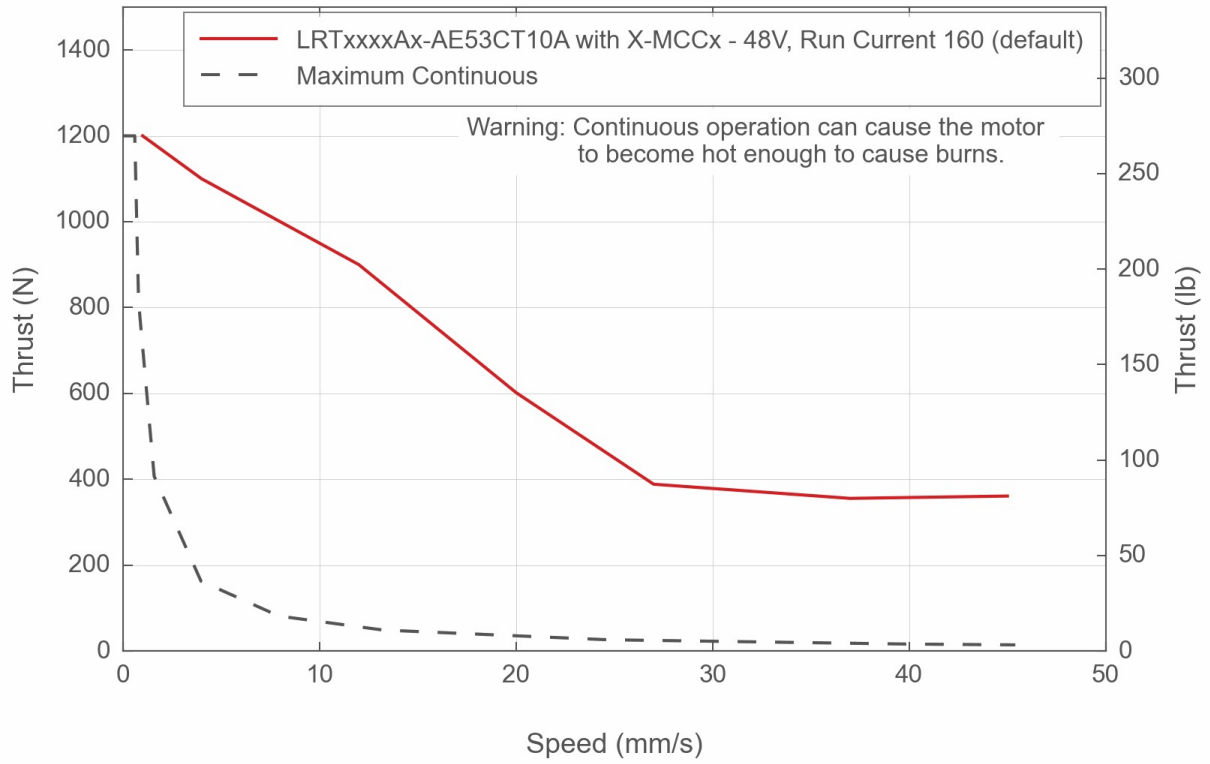
Typical Accuracy



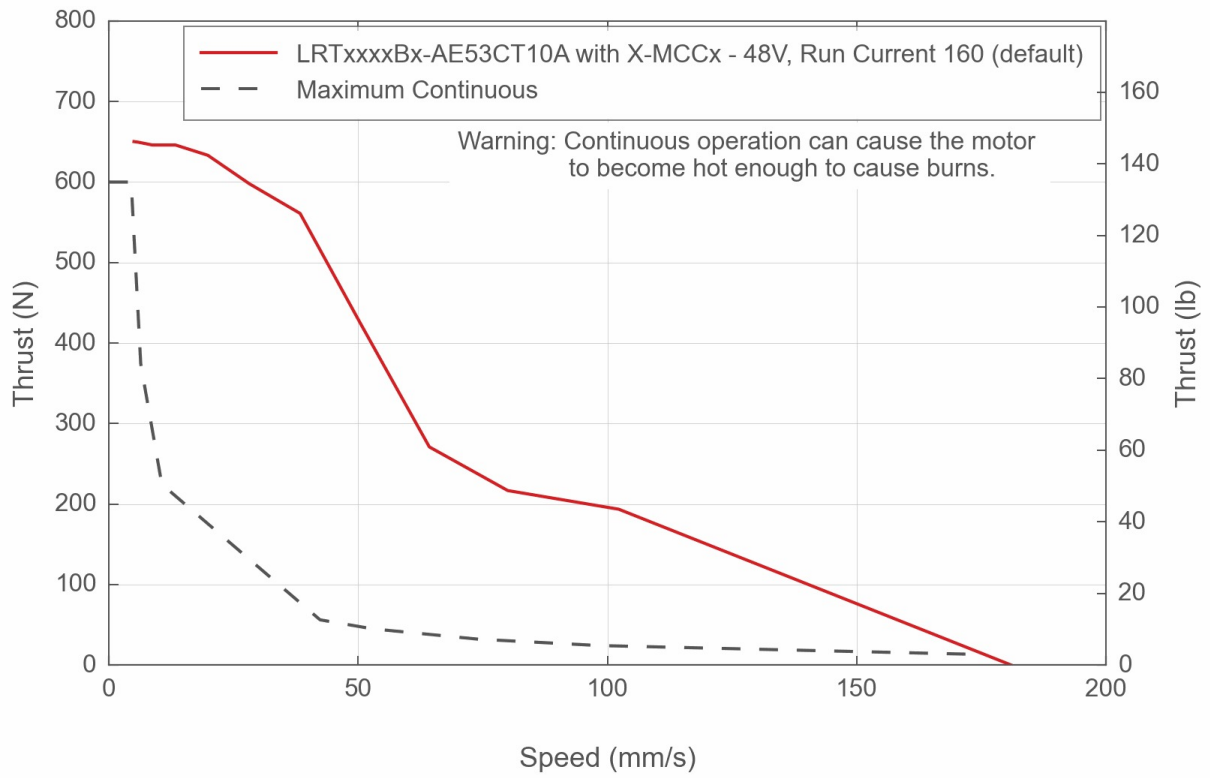
Thrust Speed Performance



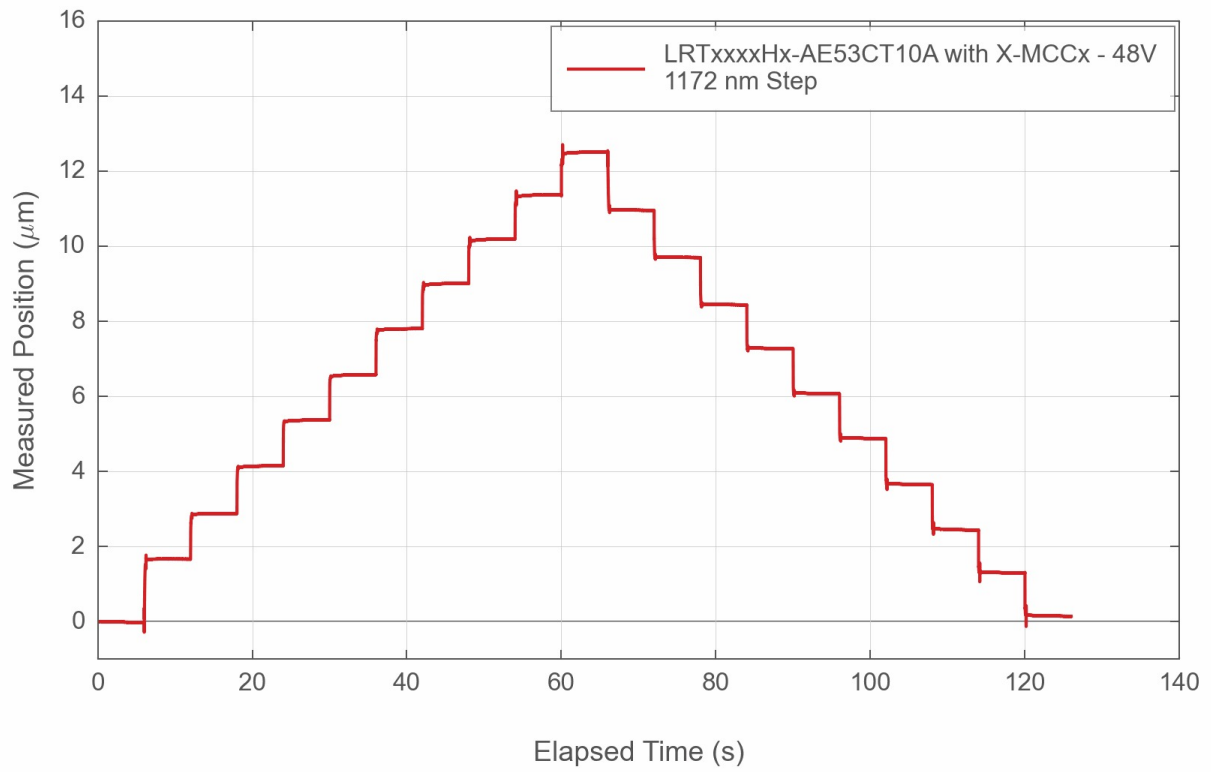
Thrust Speed Performance



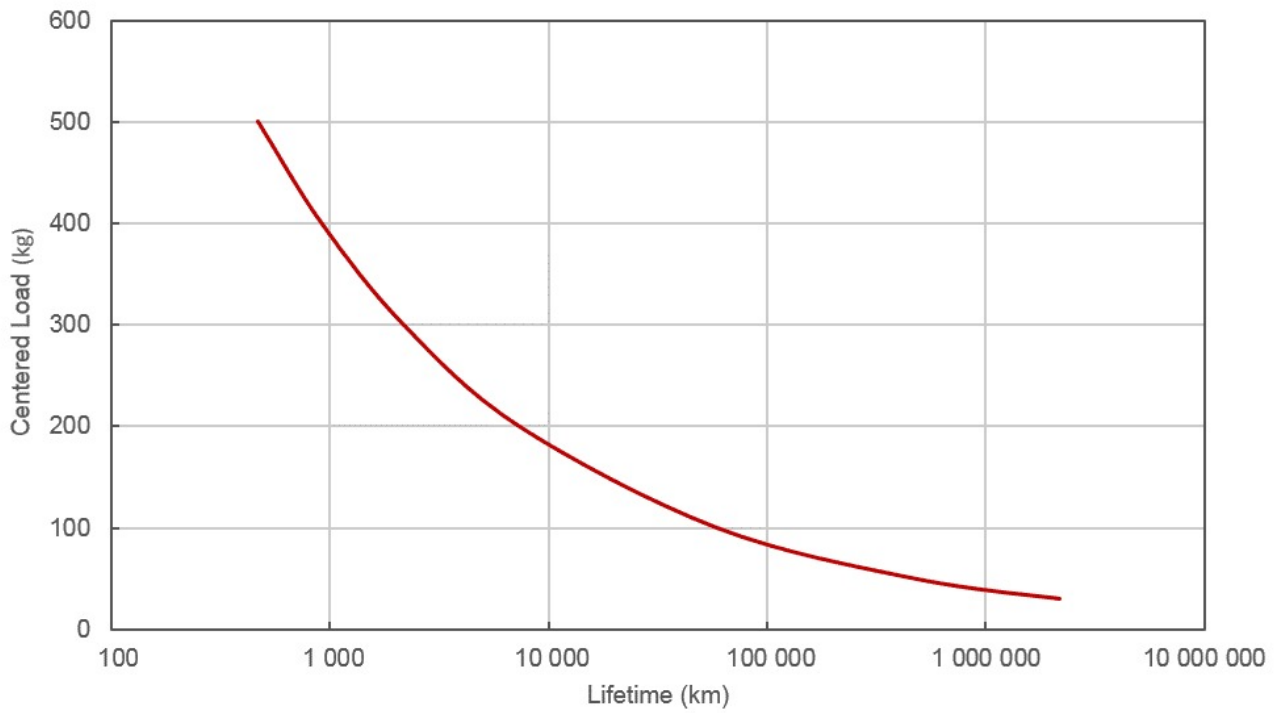
Thrust Speed Performance



Typical Minimum Incremental Move



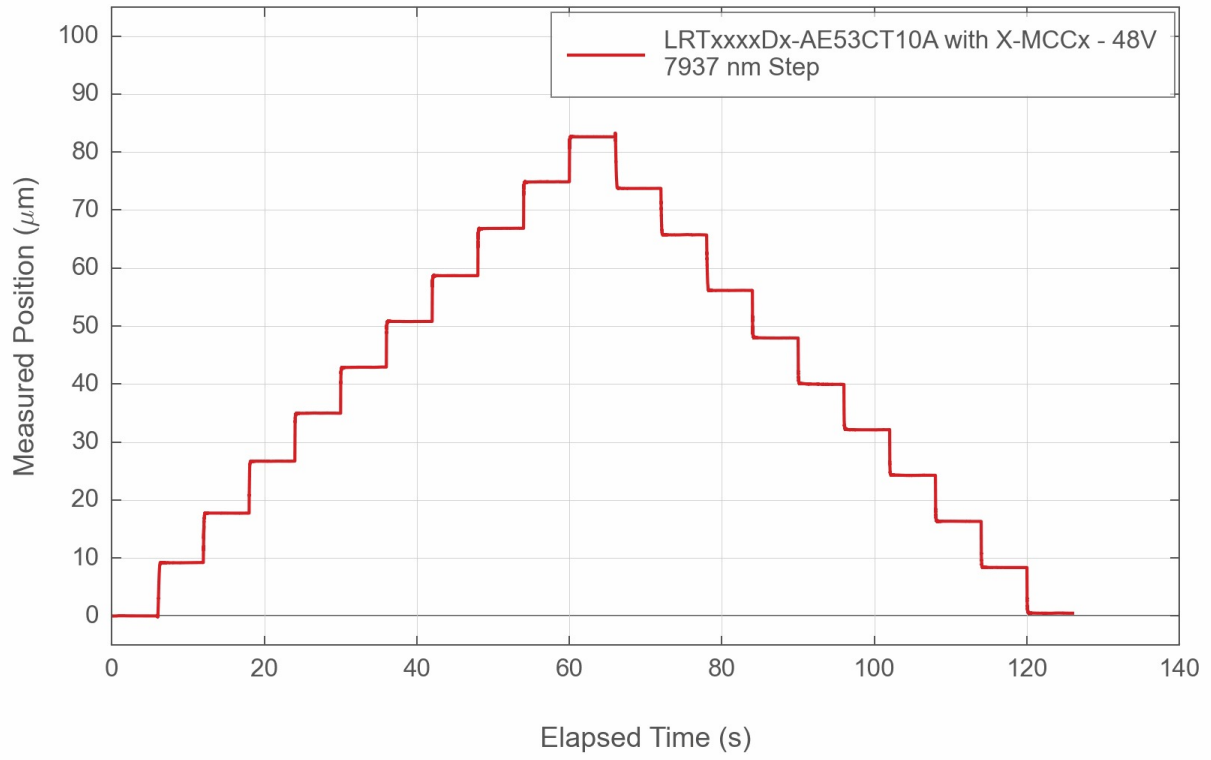
Typical LRT Bearing Lifetime



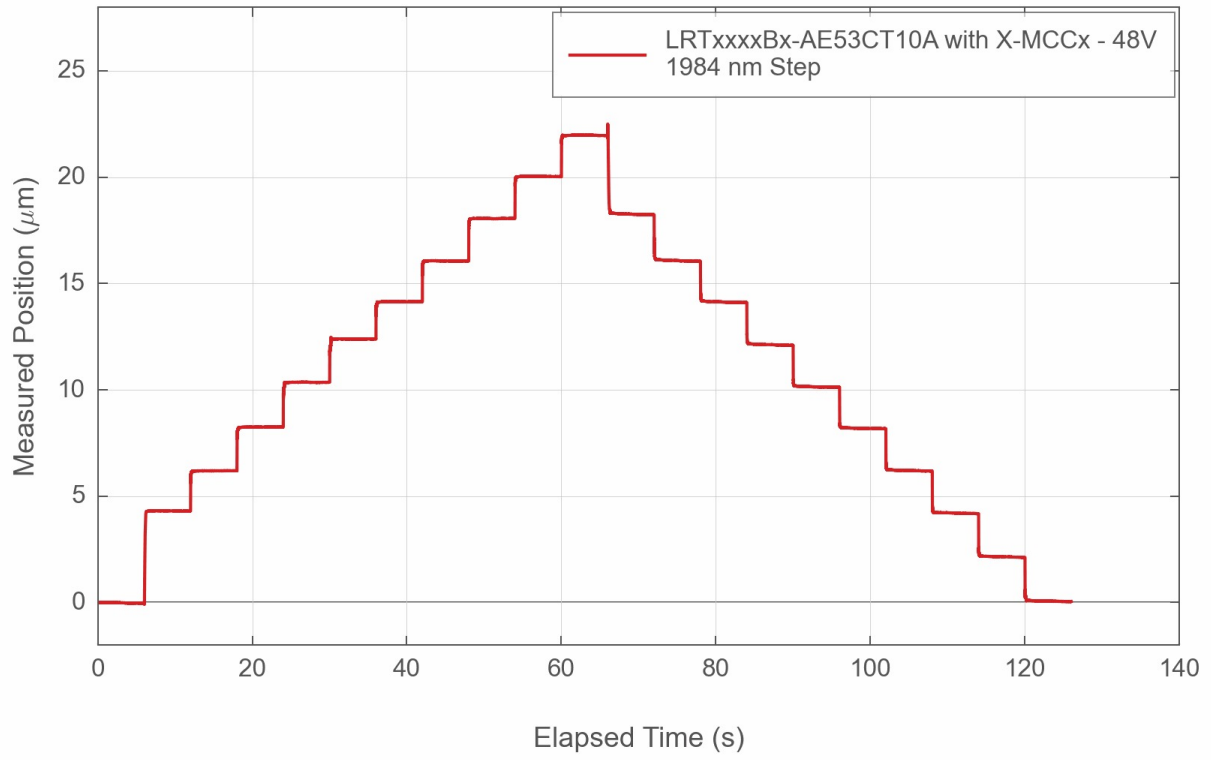
Typical Minimum Incremental Move



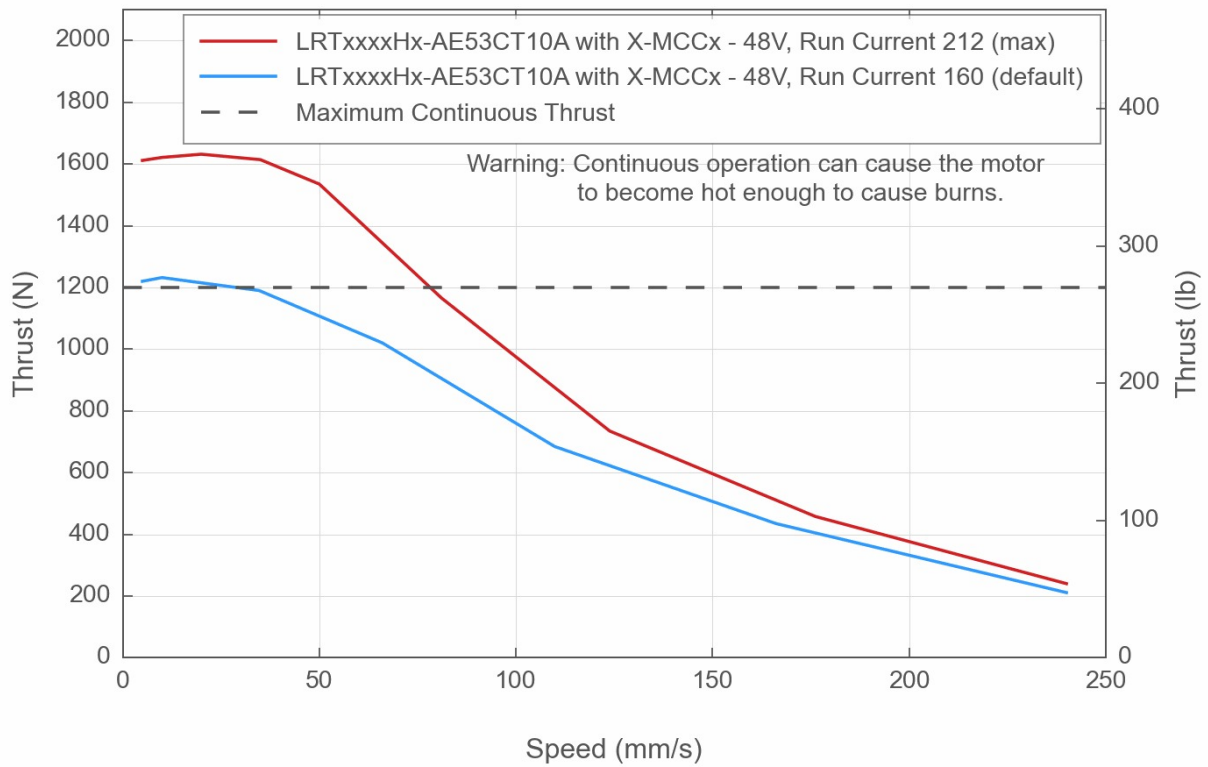
Typical Minimum Incremental Move



Typical Minimum Incremental Move



Thrust Speed Performance



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