

## LRT1000AL-E08CT3A Datasheet



- 100, 250, 500, 750, 1000, 1500 mm travel
- Up to 700 mm/s speed and up to 1200 N thrust
- 300 kg load capacity
- Ball screw and lead screw configurations
- Includes stainless steel dust covers
- High moment stiffness
- Built-in, 400 CPR, motor encoder provides slip/stall detection and recovery
- Optional integrated power-off brake for vertical applications
- Designed for use with an X-MCC Series stepper motor controller or any 2-phase stepper motor controller
- With AutoDetect, the X-MCC controller configures its settings automatically for the connected peripheral

### LRT-EC Series Overview

Zaber's LRT-EC Series products are computer-controlled, motorized linear stages with high stiffness, load, and lifetime capabilities in a compact size. A flexible stainless steel dust cover prevents the ingress of small objects. These stages can bolt together to make XY and XYZ systems. For Z-axis systems, an optional power-off brake is available to protect against backdriving. Some multi-axis configurations may require additional accessories; please contact Zaber Technical Support to ensure the correct ones are selected.

The built-in motor encoder allows for closed-loop operation and slip/stall recovery features. The stages are designed to connect directly to our X-MCC Series universal motor controllers, or they can be used with any 2-phase stepper motor controller through the panel mount DB15 connector. Set up is easy

with AutoDetect. Once connected, the X-MCC controller will automatically detect and configure the LRT-EC.

For more information visit: <https://www.zaber.com/products/linear-stages/LRT-EC>

## LRT-EC Series Part Numbering & Options



## LRT1000AL-E08CT3A Drawings

- [LRT-ECT3A.png](#) (Drawing for the LRT-ECT3A)

## LRT1000AL-E08CT3A Specifications

<b>Microstep Size (Default Resolution)</b>	<b>0.124023438 <math>\mu\text{m}</math></b>
Built-in Controller	No
Recommended Controller	X-MCC (48 V) Recommended
AutoDetect	Yes
Travel Range	1000 mm (39.370")
Accuracy (unidirectional)	250 $\mu\text{m}$ (0.009842")
Repeatability	< 4 $\mu\text{m}$ (< 0.000157")
Backlash	< 12 $\mu\text{m}$ (< 0.000472")
Maximum Speed	28 mm/s (1.102"/s)
Minimum Speed	0.000076 mm/s (0.000003"/s)
Speed Resolution	0.000076 mm/s (0.000003"/s)
Encoder Resolution	400 CPR (1600 states/rev)
Encoder Type	Rotary quadrature encoder
Peak Thrust	1200 N (269.1 lb)
Back-driving Force*	Non-back-driving
Maximum Continuous Thrust	1200 N (269.1 lb)
Maximum Centered Load	2940 N (659.3 lb)
Maximum Moment (Pitch)	70 N-m (51.7 ft-lb)
Maximum Moment (Roll)	120 N-m (88.6 ft-lb)
Maximum Moment (Yaw)	70 N-m (51.7 ft-lb)
Vertical Runout	< 10 $\mu\text{m}$ (< 0.000394")
Horizontal Runout	< 50 $\mu\text{m}$ (< 0.001968")
Pitch	0.015° (0.262 mrad)
Roll	0.02° (0.349 mrad)
Yaw	0.03° (0.523 mrad)
Stiffness in Pitch	1400 N-m/° (12 $\mu\text{rad/N-m}$ )
Stiffness in Roll	700 N-m/° (25 $\mu\text{rad/N-m}$ )
Stiffness in Yaw	1200 N-m/° (15 $\mu\text{rad/N-m}$ )
Linear Motion Per Motor Rev	1.5875 mm (0.062")
Motor Steps Per Rev	200
Motor Type	Stepper (2 phase)

<b>Microstep Size (Default Resolution)</b>	<b>0.124023438 <math>\mu\text{m}</math></b>
Motor Rated Current	3000 mA/phase
Motor Winding Resistance	0.53 ohms/phase
Inductance	2 mH/phase
Motor Connection	D-sub 15
Default Resolution	1/64 of a step
Guide Type	Recirculating Ball Linear Guide
Mechanical Drive System	Precision lead screw
Limit or Home Sensing	Magnetic home sensor
Axes of Motion	1
Operating Temperature Range	0 to 50 °C
CE Compliant	Yes
Vacuum Compatible	No
Weight	8.393 kg (18.503 lb)

# LRT-EC Series Charts

## Thrust Speed Performance



## Thrust Speed Performance



## Thrust Speed Performance



## Thrust Speed Performance



## Thrust Speed Performance



## Typical LRT Bearing Lifetime



## Contact

Email: [contact@zaber.com](mailto:contact@zaber.com)

Phone (toll free Canada/USA): 1-888-276-8033

Phone (direct): 1-604-569-3780

Fax: 1-604-648-8033

Zaber Technologies Inc.

#2 - 605 West Kent Ave. N.

Vancouver, British Columbia

Canada, V6P 6T7

<https://www.zaber.com>