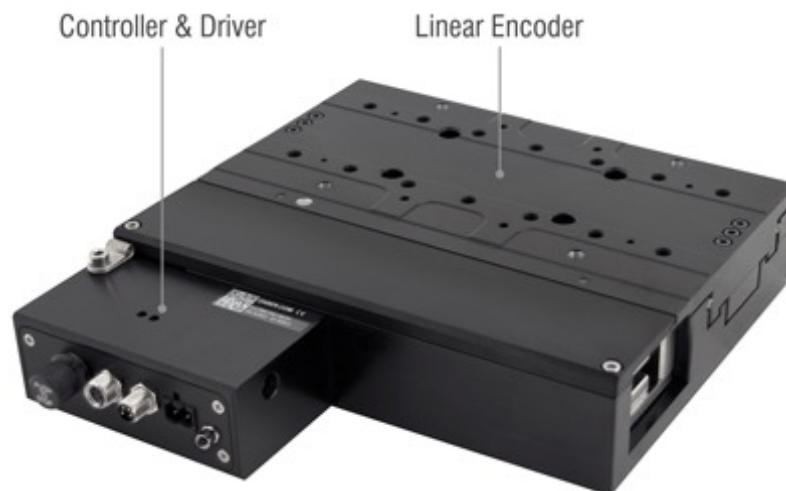


X-LDM060C-AE54D12 Datasheet



- 60, 110, 210 mm travel options
- Up to 1.2 m/s speed and up to 3.5 g acceleration
- High repeatability (80 nm) and accuracy (1 μ m), with 25 nm minimum incremental move
- Direct position measurement from 1 nm resolution linear encoder
- One digital input and two digital outputs
- Non-contact ironless linear motor for ultra precision, high dynamic performance and zero backlash
- Built-in controller; daisy-chains with other Zaber products
- Technical Article - Linear Motors: Overview and Selection Process

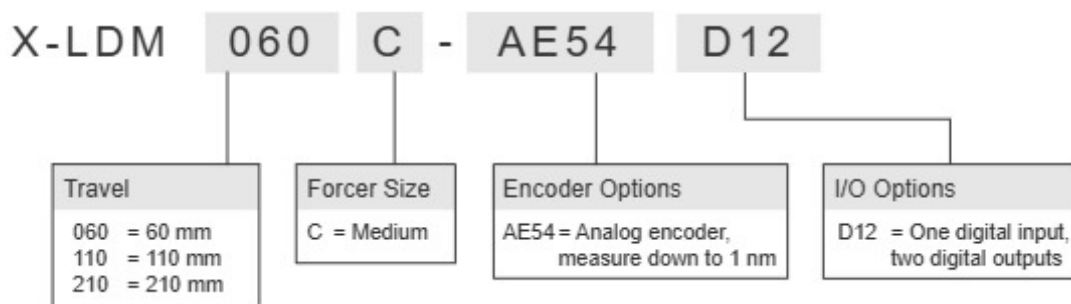
X-LDM-AE Series Overview

Zaber's X-LDM-AE Series devices are computer-controlled, motorized linear stages suited for applications demanding outstanding precision, throughput, and reliability. A centrally mounted linear encoder results in 1 μm position accuracy and consistent movement steps down to 25 nm. X-LDM-AE devices feature high efficiency ironless linear motors, providing high speed and acceleration, while minimizing heat generation to improve repeatability. Both the drive and encoder are non-contact and have no moving cables, resulting in an high lifetime system.

These stages are stand-alone units requiring only a standard 48 V power supply. They connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Like all of Zaber's products, the X-LDM-AE Series is designed to be 'plug and play' and very easy to set up and operate. X-LDM-AE devices also include a digital input and two digital outputs for interfacing with external systems. An event-driven trigger system allows devices to be programmed for stand-alone operation based on I/O, time, or movement stimuli.

For more information visit: <https://www.zaber.com/products/linear-stages/X-LDM-AE>

X-LDM-AE Series Part Numbering & Options



X-LDM060C-AE54D12 Drawings

- [dimensions_X-LDM-AE \(Drawing for the X-LDM_AE\)](#)

X-LDM060C-AE54D12 Specifications

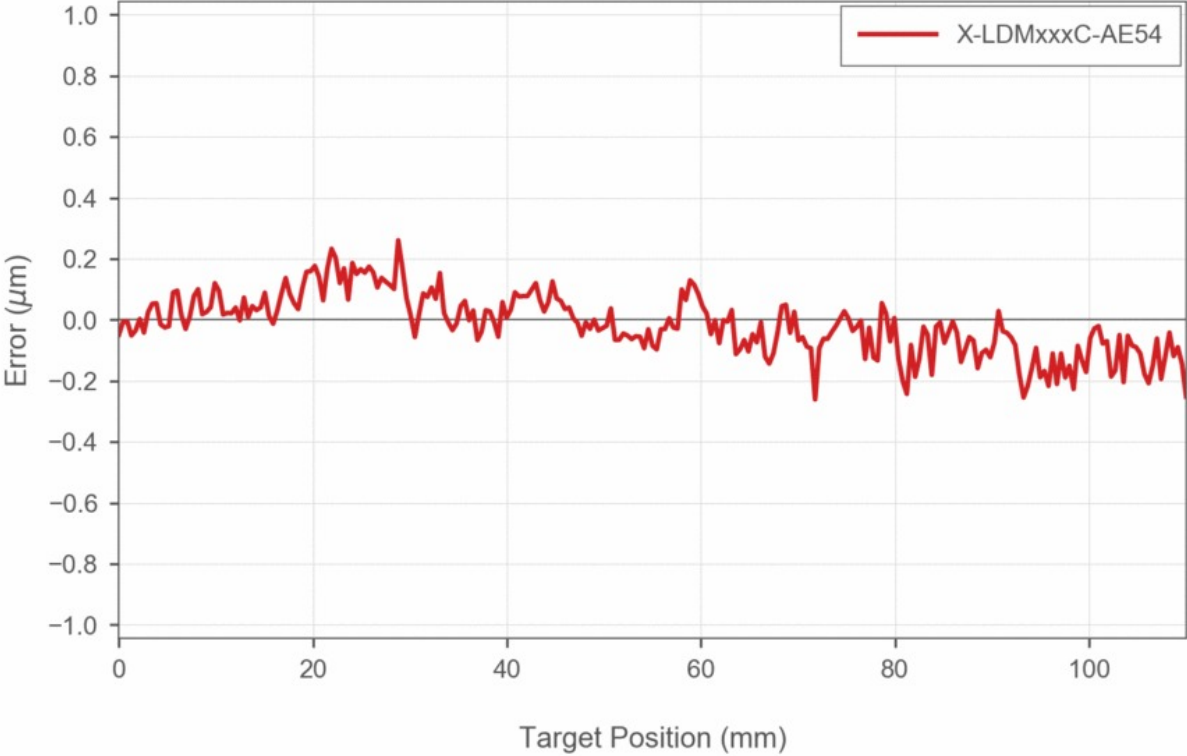
| Built-in Controller | |
|----------------------------|-----------------------------------------------|
| Travel Range | 60 mm (2.362") |
| Accuracy (unidirectional) | 1 μm (0.000039") |
| Repeatability | < 0.08 μm (< 0.000003") |
| Minimum Incremental Move | 25 nm |
| Maximum Acceleration | 34.3 m/s ² (3.50 g) |
| Maximum Speed | 1200 mm/s (47.244"/s) |
| Minimum Speed | 0.61 nm/s |
| Speed Resolution | 0.61 nm/s |
| Encoder Type | Linear analog encoder |
| Encoder Count Size | 1 nm |
| Peak Thrust | 60 N (13.5 lb) |
| Maximum Continuous Thrust | 35 N (7.8 lb) |
| Communication Interface | RS-232 |
| Communication Protocol | Zaber ASCII (Default) |
| Data Cable Connection | Locking 4-pin M8 |
| Maximum Centered Load | 185 N (41.5 lb) |
| Maximum Moment (Pitch) | 1200 N-cm (1699.3 oz-in) |
| Maximum Moment (Roll) | 1200 N-cm (1699.3 oz-in) |
| Maximum Moment (Yaw) | 1200 N-cm (1699.3 oz-in) |
| Vertical Runout | < 4 μm (< 0.000157") |
| Horizontal Runout | < 3 μm (< 0.000118") |
| Typical Velocity Stability | \pm 0.11% at 100 mm/s with a 1.0 kg payload |
| Pitch | 0.003° (0.052 mrad) |
| Roll | 0.002° (0.035 mrad) |
| Yaw | 0.002° (0.035 mrad) |
| Power Supply | 48 VDC |
| Power Plug | 2-pin screw terminal |

Built-in Controller

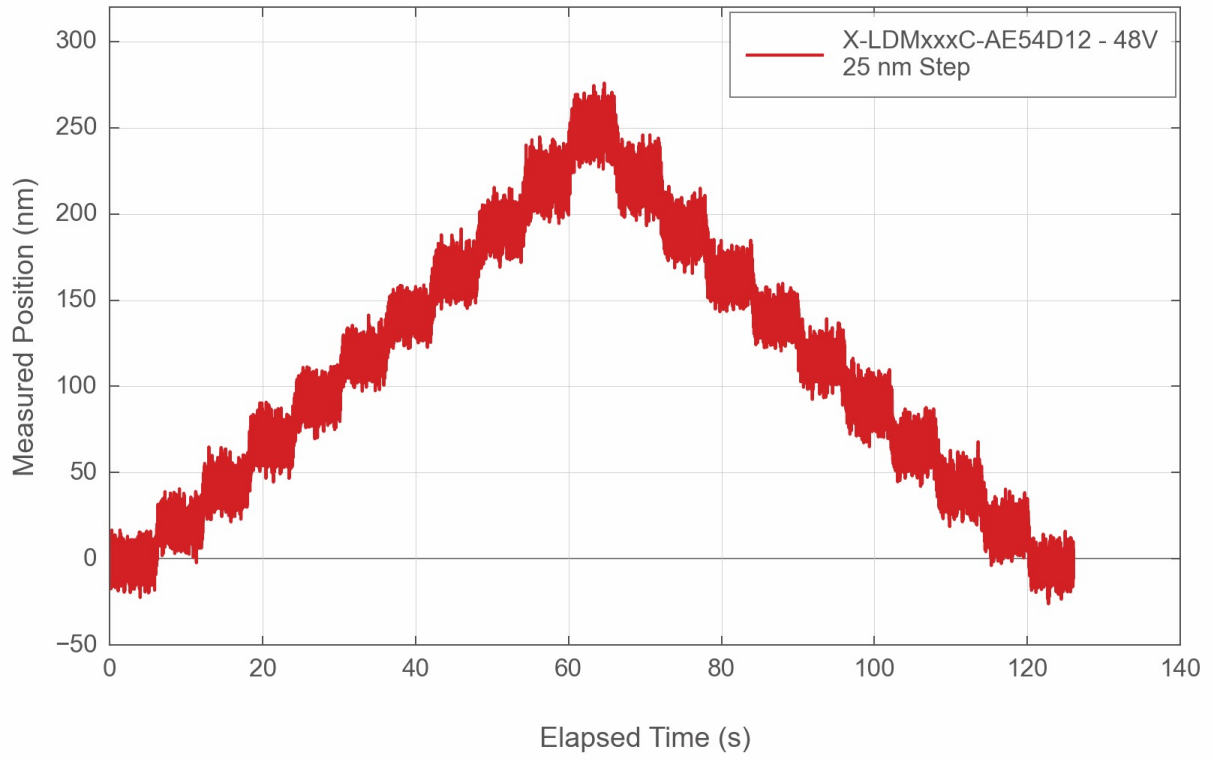
| | |
|-----------------------------|----------------------------------|
| Maximum Current Draw | 3000 mA |
| Motor Type | Moving Magnet Track Linear Motor |
| Force Constant | 15.8 N/A (3.5 lbs/A) |
| Guide Type | Crossed-Roller Bearing |
| Limit or Home Sensing | Optical Index Mark |
| Manual Control | Indexed knob with push switch |
| Axes of Motion | 1 |
| LED Indicators | Yes |
| Mounting Interface | M6 threaded holes |
| Moving Mass | 1.74 kg (3.828 lbs) |
| Digital Input | 1 |
| Digital Output | 2 |
| Operating Temperature Range | 10 to 40 °C |
| CE Compliant | Yes |
| Vacuum Compatible | No |
| Weight | 3.76 kg (8.289 lb) |

X-LDM-AE Series Charts

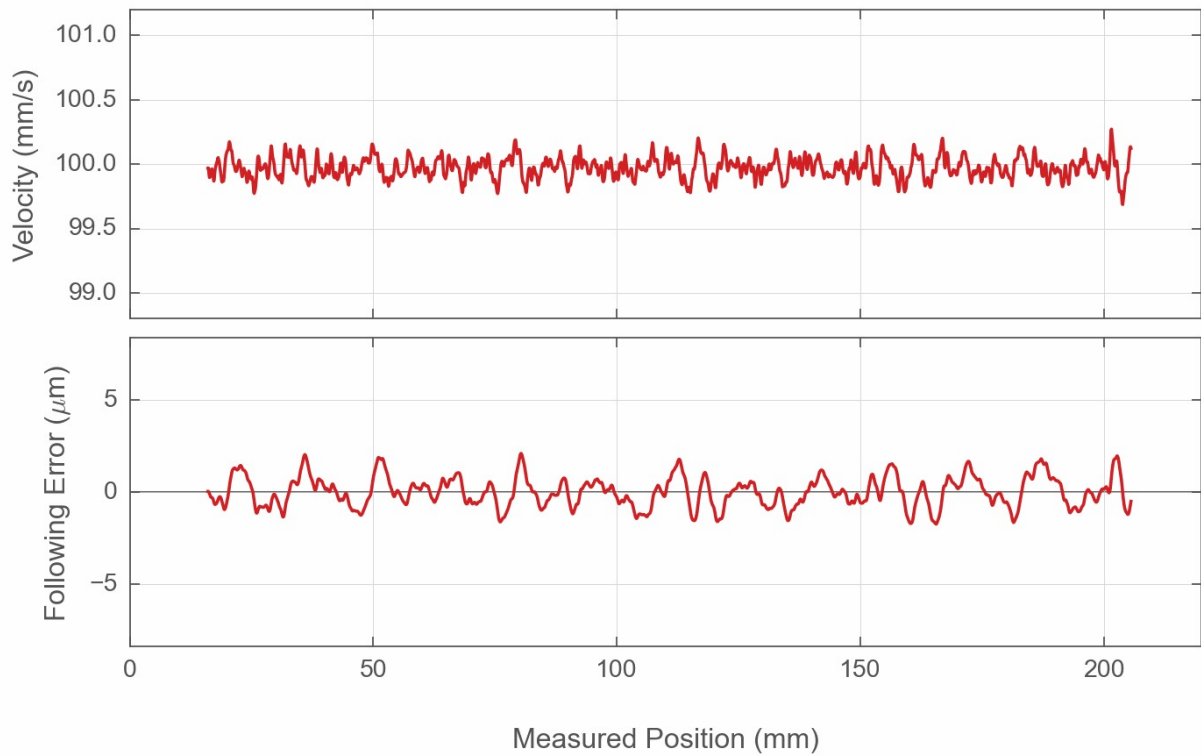
Typical Accuracy



Typical Minimum Incremental Move



Typical Velocity Stability and Following Error



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