

X-LRT0750HL-BAE53C Datasheet



- 100, 250, 500, 750, 1000, 1500 mm travel
- 20 μm full travel accuracy
- 300 kg load capacity
- Includes stainless steel dust covers
- Ball screw and lead screw configurations
- Optional integrated power-off brake for vertical applications
- Integrated linear encoders with 50 nm resolution provide slip/stall detection and position correction
- Built-in controller; daisy-chains with other Zaber products

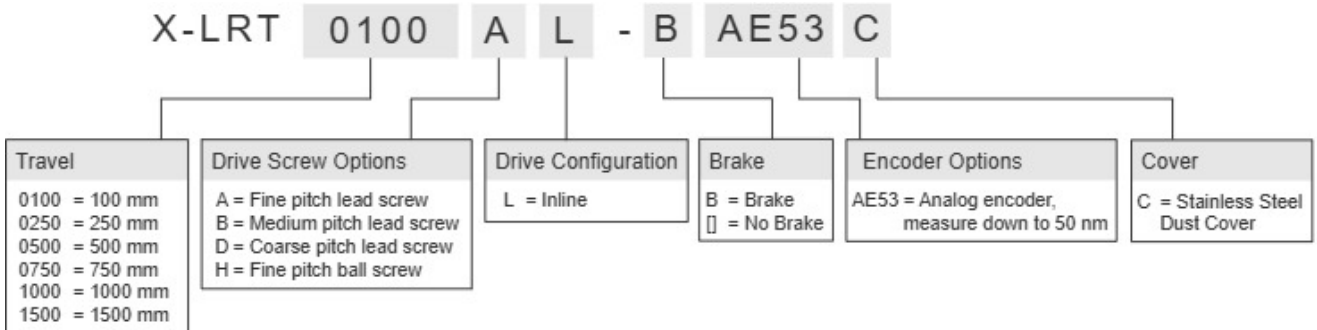
X-LRT-AEC Series Overview

Zaber's X-LRT-AEC Series are computer-controlled, motorized linear stages designed for positioning high loads to within 20 μm accuracy. An integrated linear encoder combined with stage calibration provides high accuracy positioning over the full travel of the device. They have low pitch, roll, yaw and runout and long lifetime. Flexible dust covers keep out moderate debris. An indexed knob provides convenient manual control for versatile operation even without a computer. An optional power-off brake is available to enable vertical applications with backdrivable screws.

X-LRT-AEC devices are stand-alone units requiring only a standard 48 V power supply. They connect to the RS-232 port or USB port of any computer, and can be daisy-chained with any other Zaber products. Like all of Zaber's products, the X-LRT-AEC Series is designed to be 'plug and play' and very easy to set up and operate.

For more information visit: <https://www.zaber.com/products/linear-stages/X-LRT-AEC>

X-LRT-AEC Series Part Numbering & Options



X-LRT0750HL-BAE53C Drawings

- [X-LRT-BAEC.png \(Drawing for the X-LRT-BAEC\)](#)

X-LRT0750HL-BAE53C Specifications

| | |
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| Microstep Size (Default Resolution) | 0.390625 μm |
| Built-in Controller | Yes |
| Travel Range | 750 mm (29.528") |
| Accuracy (unidirectional) | 20 μm (0.000787") |
| Repeatability | < 1.5 μm (< 0.000059") |
| Minimum Incremental Move | 1200 nm |
| Backlash | < 15 μm (< 0.000591") |
| Maximum Speed | 150 mm/s (5.905"/s) |
| Minimum Speed | 0.000239 mm/s (0.000009"/s) |
| Speed Resolution | 0.000239 mm/s (0.000009"/s) |
| Encoder Type | Linear analog encoder |
| Encoder Resolution | 50 nm |
| Peak Thrust | 1200 N (269.1 lb) |
| Back-driving Force* | (\pm 30%) 157 N (35.2 lb) |
| Maximum Continuous Thrust | 1200 N (269.1 lb) |
| Communication Interface | RS-232 |
| Communication Protocol | Zaber ASCII (Default) |
| Data Cable Connection | Locking 4-pin M8 |
| Maximum Centered Load | 2940 N (659.3 lb) |
| Maximum Moment (Pitch) | 70 N-m (51.7 ft-lb) |
| Maximum Moment (Roll) | 80 N-m (59.0 ft-lb) |
| Maximum Moment (Yaw) | 70 N-m (51.7 ft-lb) |
| Vertical Runout | < 10 μm (< 0.000394") |
| Horizontal Runout | < 50 μm (< 0.001968") |
| Pitch | 0.015° (0.262 mrad) |
| Roll | 0.02° (0.349 mrad) |
| Yaw | 0.03° (0.523 mrad) |
| Stiffness in Pitch | 1400 N-m/° (12 $\mu\text{rad/N-m}$) |
| Stiffness in Roll | 700 N-m/° (25 $\mu\text{rad/N-m}$) |
| Stiffness in Yaw | 1200 N-m/° (15 $\mu\text{rad/N-m}$) |
| Power Supply | 24-48 VDC |

| | |
|--|--|
| Microstep Size (Default Resolution) | 0.390625 μm |
| Power Plug | 2-pin screw terminal |
| Maximum Current Draw | 3600 mA |
| Linear Motion Per Motor Rev | 5 mm (0.197") |
| Motor Steps Per Rev | 200 |
| Motor Type | Stepper (2 phase) |
| Motor Rated Current | 3000 mA/phase |
| Inductance | 2 mH/phase |
| Default Resolution | 1/64 of a step |
| Guide Type | Recirculating Ball Linear Guide |
| Mechanical Drive System | Precision ball screw |
| Limit or Home Sensing | Linear Encoder Index Mark |
| Manual Control | Indexed knob with push switch |
| Axes of Motion | 1 |
| LED Indicators | Yes |
| Maximum Axial Brake Force | 1200 N (269.8 lb) |
| Operating Temperature Range | 0 to 50 °C |
| CE Compliant | Yes |
| Vacuum Compatible | No |
| Weight | 7.702 kg (16.980 lb) |

X-LRT-AEC Series Charts

Typical Microstepping Accuracy



Typical Microstepping Accuracy



Typical Microstepping Accuracy



Typical Microstepping Accuracy



Thrust Speed Performance



Thrust Speed Performance



Thrust Speed Performance



Thrust Speed Performance



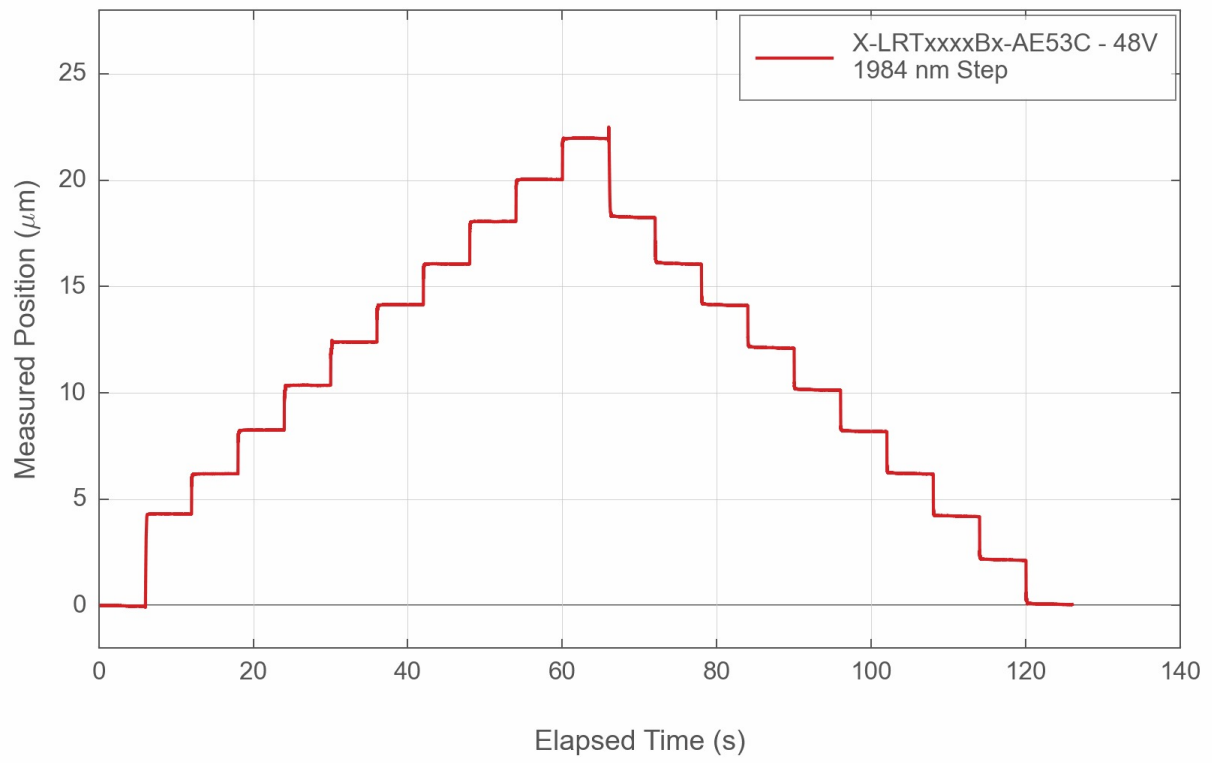
Thrust Speed Performance



Typical Minimum Incremental Move



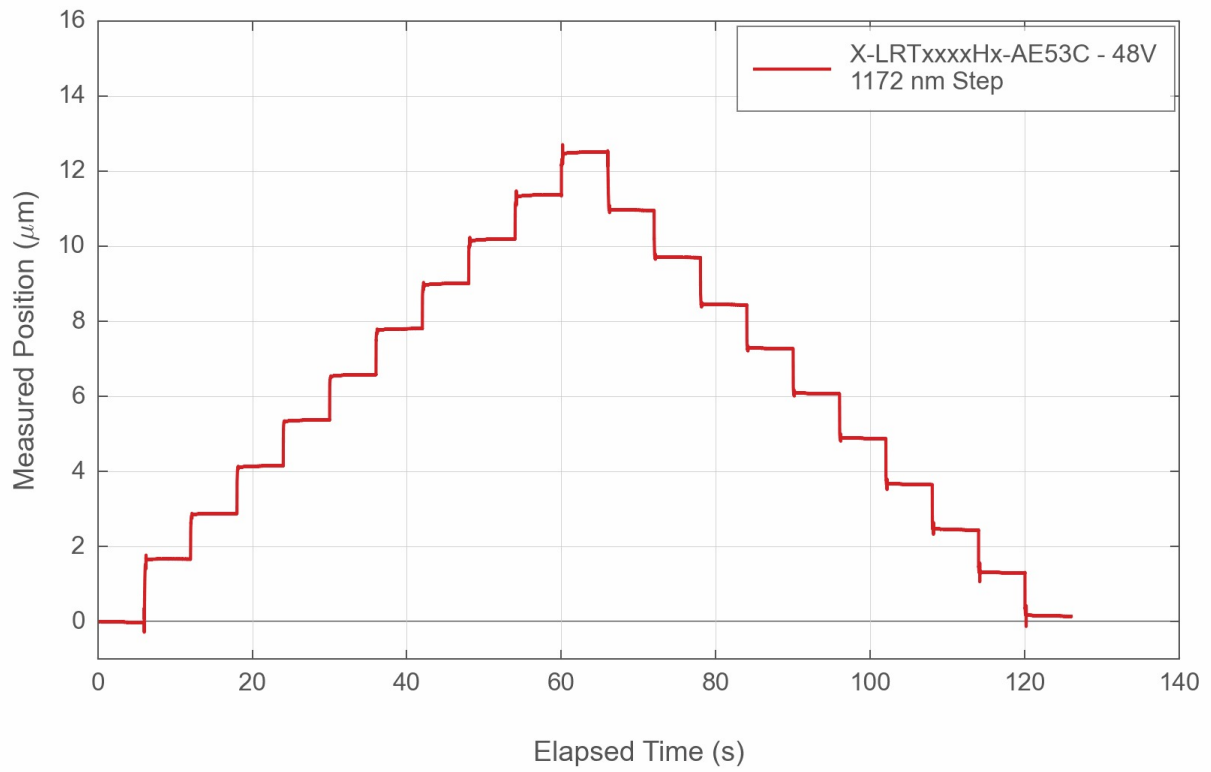
Typical Minimum Incremental Move



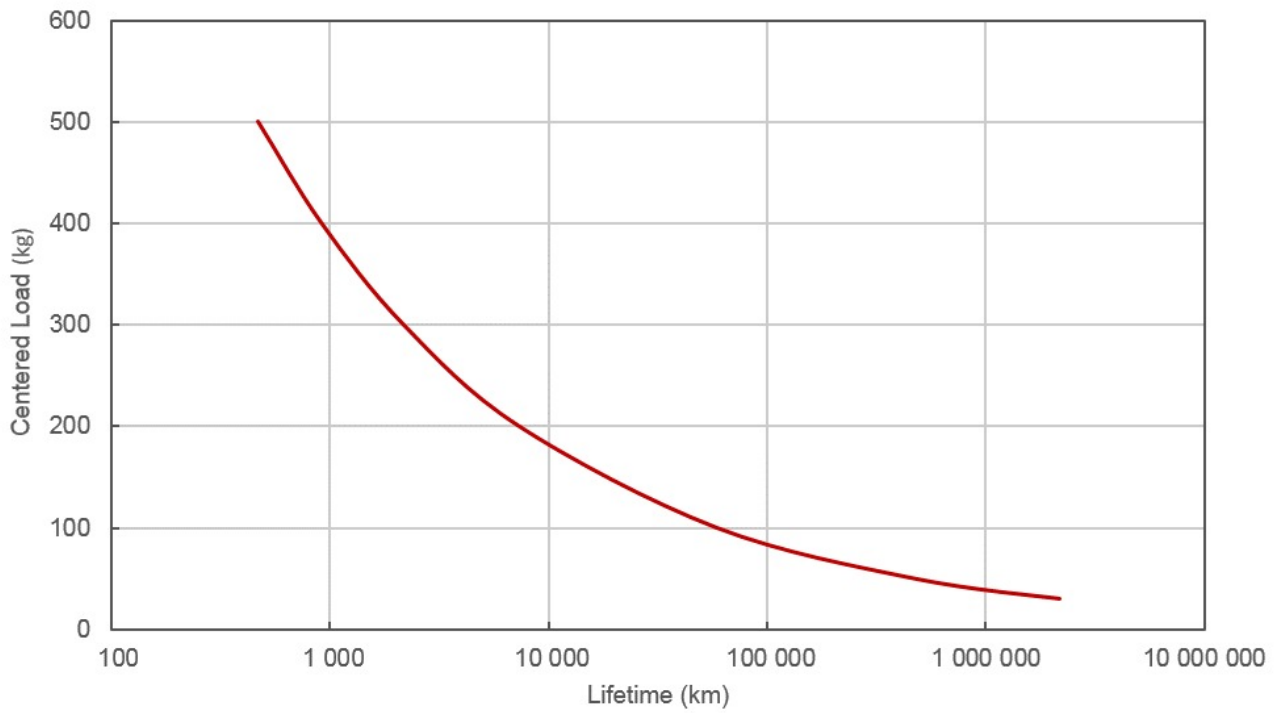
Typical Minimum Incremental Move



Typical Minimum Incremental Move



Typical LRT Bearing Lifetime



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